

[METHOD FOR OPERATING A PRE-CRASH SENSING SYSTEM IN A VEHICLE HAVING A COUNTERMEASURE SYSTEM USING A RADAR AND CAMERA]

Abstract of Disclosure

A control system for an automotive vehicle (50) has a radar or lidar system (22) used to generate a remote object signal. A vision system (26) generates an object size signal. A controller (12) is coupled to the radar (22) and the vision system (26). The controller activates a first countermeasure or the first and a second countermeasure in response to the object distance and object size signals.

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